### **UCTION MOTOR**



### □90mm

# LEAD WIRE TYPE TERMINAL BOX TYPE

K9IS40N□



K9IS40N□-T, T5



### **SPECIFICATIONS**

40W continuous rating, four poles

Mode	l	Voltage (V)	Frequency (Hz)	Current (A)	Start T. (N·m/kgf·cm)	Rated T. (N·m/kgf·cm)	Speed (rpm)	Condenser (µF)		
K9I□40NJ(-T, -T5)		100	50	0.86	0.21/2.1	0.315/3.15	1250	12		
K91040N3(-1, -13)		100	60	0.84	0.22/2.2	0.255/2.55	1550	IZ.		
K9I□40NU(-T, -T5)		110	60	0,65	0.19/1.9	0,255/2,55	1550	8		
13124010( 1, 13)		115	00	0.68	0.2/2		1550	0		
K9I□40NL(-T, -T5)		200	50	0.4	0.22/2.2	0.315/3.15	1250	3		
131040NE( 1, 13)	single-phase	200	60	0.41	0,22/2,2	0.255/2.55	1550	3		
		220	50	0.38	0.24/2.4	0.315/3.15	1250			
K9I□40NC(-T, -T5)		220	60	0.37	0,24/2,4	0.255/2.55	1550	2,5		
		230	50	0.4	0.26/2.6	0.315/3.15	1250			
		230	60	0.38	0.20/2.0	0.255/2.55	1550			
K9I□40ND(-T, -T5)		240	50	0.39	0.2/2	0.3/3	1300	2		
K9I□40NT(-T, -T5)		200	50	0.39	1/10	0.3/3	1300	_		
K91040N1(-1, -15)		200	60	0.32	0.78/7.8	0.245/2.45	1600			
		220	50	0,33	0.95/9.5	0.29/2.9	1350	_		
K9I□40NH(-T, -T5)		220	60	0.31	0.78/7.8	0.245/2.45	1600			
K91040NH(-1, -15)		000	50	0.41	1/10	0.29/2.9	1350			
		230	60	0.32	0.83/8.3	0.245/2.45	1600			
K9I□40NM(-T, -T5)	three-phase	380	50	0,18	1/10	0.29/2.9	1350	_		
K9I□40NM(=1, =15)	il liee-priase	380	60	0,10	0.78/7.8	0.245/2.45	1600			
K9I□40NV(-T, -T5)		400	50	0.18	1,15/11,5	0.29/2.9	1350	_		
N91114011V(-1, -15)		400	60	0.19	0.88/8.8	0.245/2.45	1600			
K9I□40NQ(-T, -T5)	1	/1E	50	0.16	0.95/9.5	0.29/2.9	1350	-		
N91114011Q(-1, -15)		415	60	0.14	0.72/ 7.2	0.245/2.45	1600			
KOLD 40NZ( T TE)	1	440	50	0.19	1/10	0.29/2.9	1350	_		
K9I□40NZ(-T, -T5)		440	60	0.16	0.79/7.9	0.245/2.45	1600	_		

\* : SHAFT SHAPE (S : STRAIGHT, G : PINION) \* NU, NH, NH-T, NH-T5 which are in end of the model name is UL certified ones. UL FILE NO. E204632

### RATED TORQUE OF GEARHEAD

• 50Hz

00112																					unit :	= above	: N·m /	below:	Kgf∙cm
Model	Speed(rpm)	500	416	300	250	200	166	150	120	100	83	75	60	50	41	37	30	25	20	16	15	12.5	10	8.3	7.5
Motor/	ороса(гріп)	000	710	000	200	200	100	100	120	100	-00	, 0	- 00	00	71	01	00	20	20	0	Ō	1.0	10	0.0	
Gearhead	Ratio	3	3.6	5	6	7.5	9	10	12,5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
K9I□40N□	(-T, -T5)	0.70	0.85	1,17	1,41	1.76	2,11	2,35	2,94	3,52	4,23	4.23	5,29	6.34	7.61	8.46	10	10	10	10	10	10	10	10	10
K9G□	1B(C)	7.0	8.5	11.7	14.1	17.6	21.1	23.5	29.4	35.2	42.3	42.3	52.9	63.4	76.1	84.6	100	100	100	100	100	100	100	100	100

### 60Hz

00112																					unit =	above	: N·m /	below:	Kgf∙cm
Model	Speed(rpm)	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
Motor/	opecu((piii)	000	000	000	000	240	200	100	177	120	100	00	''	00	00	70	00	00		20	10	10	12	10	
Gearhead	Ratio	3	3,6	5	6	7.5	9	10	12,5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
K9I□40N□	1(-T, -T5)	0,60	0.71	0.99	1,19	1.49	1.79	1,98	2,48	2,98	3.57	3.57	4.47	5,36	6.43	7.14	8.04	10	10	10	10	10	10	10	10
K9G	1B(C)	6.0	7.1	9.9	11.9	14.9	17.9	19,8	24.8	29.8	35.7	35,7	44.7	53,6	64.3	71.4	80.4	100	100	100	100	100	100	100	100

- Gearhead and decimal gearhead are sold separately.
- \* The code in  $\hfill\Box$  of gearhead model is for gear ratio.
- \* color indicates that the output shaft of the geared motor rotates in the same direction as the output shaft of the motor. Others indicate rotation in the opposite direction.
- \* If you are to have less ratio than the ratio in the table, you can install the decimal gearhead, which has one tenth of the ratio, between the gearhead and the motor. In this case, the permissible torque is 10N·m/100kgf·cm.
- \* RPM is based on motor's synchronous rpm (50HZ:1500rpm, 60HZ:1800rpm) and calculated by dividing gear ratio. Actual rpm is 2~20% less than B-16 indicating rpm according to load size.

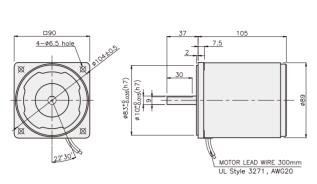
<sup>\* 3</sup> phase motor for over 380 voltage can't be used with inverter. Motor winding insulation can be damaged.

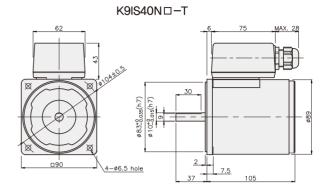
### **GGM** GGM GEARED MOTOR

### **GEARHEAD**

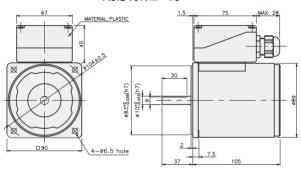
### **DIMENSIONS**

### K9IS40N□



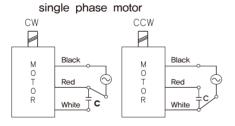


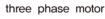
#### K9IS40N□-T5

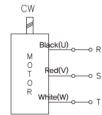


### **CONNECTION DIAGRAMS**

### K9IS40N□



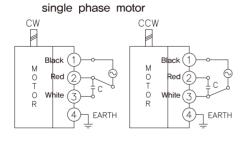




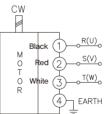
connecting two leadwires of U,V,W in turns

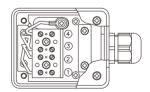
\*\*The direction of motor rotation is as viewed from the front shaft end of the motor

### K9IS40N□-T



#### three phase motor

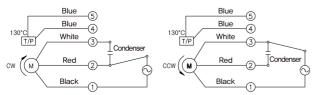




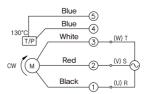
\*The direction of motor rotation is as viewed from the front shaft end of the motor

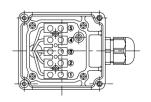
### K9IS40N □-T5

### single phase motor



### three phase motor





\*\*The direction of motor rotation is as viewed from the front shaft end of the motor



## GEARHEAD

### **DIMENSIONS**

K9G□B(C)

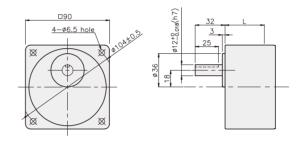


DECIMAL GEARHEAD **K9G10BX** 

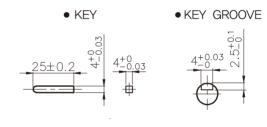
18 37 4-\varphi 6.5 hole

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GEARHEAD **K9G□B(C)** 



### **KEY SPEC**



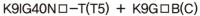
## **GGM** GGM GEARED MOTOR

### **GEARHEAD**

### **DIMENSIONS**

K9IG40N□ + K9G□B(C)







#### DIMENSION TABLE

PART No	L	Application Model	Mounting BOLT
01	42	K9G3~18B(C)	M6 P1,0 X 65
02	60	K9G20~200B(C)	M6 P1,0 X 80
03	37	K9G10BX	M6 P1,0 X 120

#### WEIGHT

	PART	WEIGHT(kg)				
	MOTOR	2,36				
DECIM	AL GEARHEAD	0,60				
	K9G3~18B(C)	0,78				
GEAR	K9G20~40B(C)	1,04				
	K9G50~200B(C)	1,14				

### DIMENSION TABLE

PART No	L	Application Model	Mounting BOLT
01	42	K9G3~18B(C)	M6 P1.0 X 65
02	60	K9G20~200B(C)	M6 P1.0 X 80
03	37	K9G10BX	M6 P1.0 X 120

### WEIGHT

	PART	WEIGHT(kg)				
	MOTOR	2,52				
DECIM	AL GEARHEAD	0,60				
	K9G3~18B(C)	0,78				
GEAR	K9G20~40B(C)	1,04				
	K9G50~200B(C)	1,14				

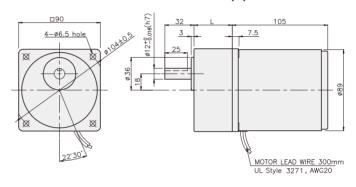
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03	37	K9G10BX	M6 P1.0 X 120

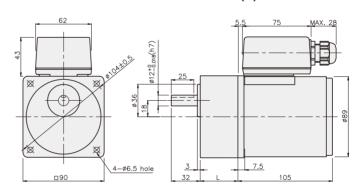
#### WEIGHT

WEIGHT									
	PART	WEIGHT(kg)							
	MOTOR	2,52							
DECIM	AL GEARHEAD	0.60							
GEAR HEAD	K9G3~18B(C)	0,78							
	K9G20~40B(C)	1.04							
	K9G50~200B(C)	1,14							

### **K9IG40N**□ + **K9G**□**B**(**C**)



### $K9IG40N\Box$ -T + $K9G\Box$ B(C)



### K9IG40N□-T5 + K9G□B(C)

