

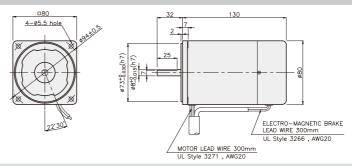
# **BRAKE MOTOR**



# □80mm

# K8□S25N□-B





### SPECIFICATIONS

25W single-phase : 30 minutes rating, three-phase : continuous rating, four poles

Mode	el	Duty	Voltage (V)	Frequency (Hz)	Current (A)	Start T. (N∗m/ Kgf∗cm)	Rated T. (N*m/ Kgf*cm)	Speed (rpm)	Condenser (µF)	Friction T. (N*m/ (Kgf*cm)	
K8R□25NJ-B			100	50	0,65	0,15/1,5	0.195/1.95	1250	10	0,4/4	
KOK LI ZUNU-B			100	60	0.74	0.13/1.3	0.165/1.65	1500	10	0.4/4	
K8R□25NU-B			110	60	0.51	0,13/1,3	0.165/1.65	1500	6	0.4/4	
NONE ZONO D			115	00	0.54	0.10/1.0	0.100/1.00	1500	Ŭ	0.4/4	
K8R□25NL-B			200	50	0.33	0.16/1.6	0.195/1.95	1250	2.5	0.4/4	
KOK LIZONE L	single-phase	30 minutes	200	60	0.37	0,10/1.0	0.16/1.6	1550	2.5	0.4/4	
			220	50	0.29	0,15/1,5	0.195/1.95	1250			
K8R□25NC-B			220	60	0.34	0.13/1.3	0.165/1.65	1500	2	0.4/4	
RONLIZSING D			230	50	0.35	0,165/1,65	0.195/1.95	1250		0.4/4	
			250	60	0.34	0.103/1.03	0.165/1.65	1500			
K8R□25ND-B			240	50	0.32	0.15/1.5	0.19/1.9	1300	1.5	0.4/4	
K8I□25NT-B			200	50	0.27	0.5/5	0.19/1.9	1300	_	0.4/4	
KOILIZJIII-D			200	60	0.24	0.4/4	0.16/1.6	1550		0.4/4	
			220	50	0.28	0,6/6	0.185/1.85	1350	_		
K8I□25NH-B			220	60	0.24	0.48/4.8	0.155/1.55	1600		0.4/4	
KOILIZJINII-B			230	50	0.29	0.65/6.5 0.185/1.85		1350		0.4/4	
			230	60	0.25	0.52/5.2	0.155/1.55	1600			
K8I□25NM-B	three-phase	continuous	380	50	0.17	0.6/6	0.19/1.9	1300	_	0.4/4	
KOI LI ZJINIVI LI	linee phase	Corilliadus	360	60	0.14	0.48/4.8	0.155/1.55	1600		0.4/4	
K8I□25NV-B			400	50	0.17	0.73/7.3	0.19/1.9	1300		0.4/4	
NOILIZDINV-B			400	60	0.15	0,6/6	0.155/1.55	1600		0.4/4	
K8I□25NQ-B			415	50	0,13	0.55/5.5	0.19/1.9	1300		0.4/4	
NOILI ZUNQ-D			410	60	0.11	0.4/4	0.155/1.55	1600		0.4/4	
V01□ 25N7_D			440	50	0.14	0.63/6.3	0.19/1.9	1300		0.4/4	
K8I□25NZ-B			440	60	0.12	0.5/5	0.155/1.55	1600		0.4/4	

- \* : SHAFT SHAPE (S : STRAIGHT, G : PINION) \* NH-B, NU-B which are in end of the model name is UL certified ones.UL FILE NO. E204632
- st 3 phase motor for over 380 voltage can't be used with inverter. Motor winding insulation can be damaged.

### RATED TORQUE OF GEARHEAD

### 50Hz

unit = above :  $N \cdot m$  / below :  $Kgf \cdot cm$ 

Model	Speed(rpm)	500	46	300	250	200	166	150	120	100	83	75	60	50	41	37	30	25	20	16	15	12,5	10	8,3	7.5	6
Motor/ Gearhead	Ratio	3	3,6	5	6	7.5	9	10	12,5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200	250
K8□G2	25N□-B	0.45	0.54	0.75	0.90	1,12	1,35	1.50	1,87	2,25	2.70	2.70	3.37	4.05	4.86	5.39	6.07	7,28	8	8	8	8	8	8	8	8
K8G	□B(C)	4.5	5.4	7,5	9.0	11,2	13,5	15.0	18,7	22,5	27.0	27.0	33,7	40.5	48,6	53,9	60,7	72,8	80	80	80	80	80	80	80	80

## ● 60Hz

unit = above : N·m / below : Kgf·cm

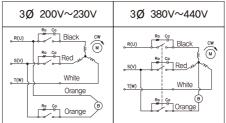
Model	Speed(rpm)	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9	7,2
Motor/ Gearhead	Ratio	3	3,6	5	6	7.5	9	10	12,5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200	250
K8□G2	5N□-B	0.38	0.45	0.63	0.75	0.94	1,13	1,26	1.57	1.88	2,26	2,26	2,82	3,39	4.07	4.52	5.08	6.10	7.63	8	8	8	8	8	8	8
K8G□	B(C)	3,8	4.5	6.3	7.5	9.4	11,3	12,6	15,7	18.8	22,6	22,6	28,2	33,9	40,7	45,2	50,8	61.0	76,3	80	80	80	80	80	80	80

- \* Gearhead and decimal gearhead are sold separately. \* The code in  $\square$  of gearhead model is for gear ratio.
- \* color indicates that the output shaft of the geared motor rotates in the same direction as the output shaft of the motor. Others indicate rotation in the opposite direction.
- \* If you are to have less ratio than the ratio in the table, you can install the decimal gearhead, which has one tenth of the ratio, between the gearhead and the motor, In this case, the permissible torque is 8N·m/80kgf·cm. But, if you install 1/25~1/40 gearhead, the permissible torque is 6N·m/60kgfcm.
- \* RPM is based on motor's synchronous rpm (50HZ:1500rpm, 60HZ:1800rpm) and calculated by dividing gear ratio. Actual rpm is  $2\sim20\%$  less than indicating rpm according to load size.



### single phase motor CW White M O T M O T O R Red O R Black R Orange Orange Rom BRAKE CAPACITOR CAPACITOR

### three phase motor



connecting two leadwires of U,V,W in turns

\*The direction of motor rotation is as viewed from the front shaft end of the motor

Connect Cr circuit for absorbing serge voltage as connection diagram to protect contact point. Ro =  $5-200\Omega$  Co =  $0.1 \sim 0.2\mu\text{F}$  200WV(400WV)

# K8G□B(C)

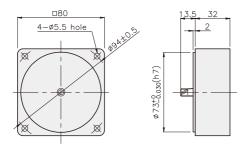


## $K8\square G25N\square -B + K8G\square B(C)$



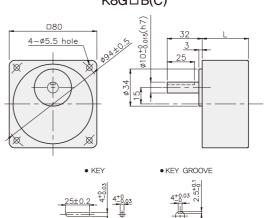
# DECIMAL GEARHEAD

# K8G10BX



### **GEARHEAD**

## K8G□B(C)



### **DIMENSION TABLE**

PART No		Application Model	Mounting BOLT
01	32	K8G3~18B(C)	M4 P0,8 X 50
02	42,5	K8G20~250B(C)	M4 P0.8 X 65
03	32	K8G10BX	M4 P0,8 X 95

# **WEIGHT**

	PART	WEIGHT(kg)
	MOTOR	1,84
DECIM/	L GEAR HEAD	0.46
	K8G3~18B(C)	0,51
GEAR	K8G20~40B(C)	0,64
	K8G50~250B(C)	0,70

## $K8\square G25N\square -B + K8G\square B(C)$

