

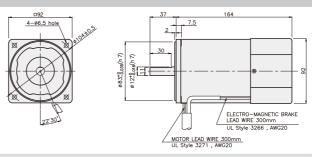
## **BRAKE MOTOR**



## □90mm

#### K9□P60F□-B





60W single-phase : 30 minutes rating, three-phase : continuous rating, four poles

Mode	el	Duty	Voltage (V)	Frequency (Hz)	Current (A)	Start T. (N*m/ Kgf*cm)	Rated T. (N*m/ Kgf*cm)	Speed (rpm)	Condenser (µF)	Friction T. (N*m/ (Kgf*cm)	
K9R□60FJ-B			100	50	1.48	0,48/4,8	0.47/4.7	1250	25	1/10	
K9KLI60FJ-B			100	60	1,66	0.40/4.0	0.38/3.8	1550	25	1/10	
K9R□60FU-B			110	- 60	1,25	0.4/4	0,38/3,8	1550	17	1/10	
Kak Loof o B			115	00	1,31	0.425/4.25	0.30/3.6		17	1/10	
K9R□60FL-B			200	50	0.72	0.5/5	0.47/4.7	1250	6	1/10	
K9KLI OUFL-B	single-phase	30 minutes	200	60	0.76	0.44/4.4	0.39/3.9	1500	0	1/10	
			220	50	0.69	0.45/4.5	0.47/4.7	1250			
K9R□60FC-B			220	60	0.76	0.48/4.8	0.38/3.8	1550	5	1/10	
N9KLIOUFC-B			230	50	0.77	0.5/5	0.47/4.7	1250		1/10	
			230	60	0.79	0.5/5	0.38/3.8	1550			
K9R□60FD-B			240	50	0.75	0.5/5	0.47/4.7	1250	5	1/10	
K9I□60FT-B			200	50	0.49	1,35/13,5	0.45/4.5	1300		1/10	
N9ILI OUF I -B			200	60	0.45	1.05/10.5	0.38/3.8	1550		1/10	
				220	50	0.55	1,6/16	0.435/4.35	1350		
K9I□60FH-B			220	60	0.47	1,2/12	0,37/3,7	1600	1 _	1/10	
K9ILI OUFH-B			230	50	0.6	1.65/16.5	0.435/4.35	1350		1/10	
			230	60	0.52	1,3/13	0.37/3.7	1600			
K9I□60FM-B	three-phase	continuous	380	50	0.34	1.55/15.5	0.435/4.35	1350	_	1/10	
K9I LI OUF IVI - B	Tillee priase	Coritiriadas	300	60	0.25	1,19/11,9	0.37/3.7	1600		1/10	
K9I□60FV-B			400	50	0.37	1.85/18.5	0.435/4.35	1350	_	1/10	
K9ILI OUF V-B			400	60	0.28	1.42/14.2	0.37/3.7	1600		1/10	
K9I□60FQ-B			415	50	0.26	1.45/14.5	0.45/4.5	1300		1/10	
Vali On La_D			415	60	0.21	1,15/11,5	0.37/3.7	1600		1/10	
K9I□60FZ-B			440	50	0.28	1,6/16	0.45/4.5	1300		1/10	
NOIL OUT Z - D			440	60	0,23	1,25/12,5	0.37/3.7	1600		1,10	

- \* □: SHAFT SHAPE (S: STRAIGHT, P: PINION) \* FH-B which are in end of the model name is UL certified ones.UL FILE NO. E204632
- \* 3 phase motor for over 380 voltage can't be used with inverter. Motor winding insulation can be damaged.

### • 50Hz

unit = above :  $N \cdot m$  / below :  $Kgf \cdot cm$ 

																									$\overline{}$
Model	Speed(rpm)	500	416	300	250	200	166	150	120	100	83	75	60	50	41	37	30	25	20	16	15	12,5	10	8,3	7.5
Motor/ Gearhead	Ratio	3	3,6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
K9□60	)F□−B	1.06	1,27	1.76	2.11	2,64	3.17	3 <u>.</u> 52	3,96	4.76	5.71	6.34	7.14	8.56	10.27	11,42	14.27	17.12	20	20	20	20	20	20	20
K9P□	B, BF	10,6	12,7	17.6	21,1	26,4	31,7	35,2	39,6	47.6	57.1	63,4	71.4	85,6	102,7	114,2	142,7	171,2	200	200	200	200	200	200	200

#### 60Hz

unit = above :  $N \cdot m$  / below :  $Kgf \cdot cm$ 

Model	Speed(rpm)	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
Motor/ Gearhead	Ratio	3	3,6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
K9□60	)F□−B	0.90	1,08	1,50	1,80	2,25	2,70	3,00	3.37	4.05	4.86	5.39	6.07	7.28	8.74	9.71	12.14	14.57	16.39	19,66	20	20	20	20	20
K9P□	B, BF	9.0	10,8	15,0	18,0	22,5	27.0	30,0	33,7	40.5	48.6	53,9	60,7	72,8	87.4	97.1	121,4	145,7	163.9	196.6	200	200	200	200	200

- \* Gearhead and decimal gearhead are sold separately. \* The code in 
  of gearhead model is for gear ratio.

  \* color indicates that the output shaft of the geared motor rotates in the same direction as the output shaft of the motor. Others indicate rotation in the opposite direction.
- \* If you are to have less ratio than the ratio in the table, you can install the decimal gearhead, which has one tenth of the ratio, between the gearhead and the motor, In this case, the permissible torque is 20N·m/200kgf·cm.
- \* RPM is based on motor's synchronous rpm (50HZ:1500rpm, 60HZ:1800rpm) and calculated by dividing gear ratio. Actual rpm is 2~20% less than indicating rpm according to load size.



## **GGM** GGM GEARED MOTOR

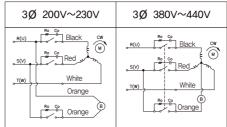
## **GEARHEADS**

CAPACITOR

#### CONNECTION DIAGRAMS

# single phase motor CW White CCW White CCW White CCW SW2 M Red Orange Black R Orange BRAKE Orange BRAKE Orange BRAKE Orange BRAKE Orange BRAKE Orange

#### three phase motor



connecting two leadwires of U,V,W in turns

\*\*The direction of motor rotation is as viewed from the front shaft end of the motor

Connect Cr circuit for absorbing serge voltage as connection diagram to protect contact point. Ro =  $5 - 200\Omega$  Co =  $0.1 \sim 0.2\mu$ F 200WV(400WV)

#### DIMENSIONS

К9Р□В

CAPACITOR

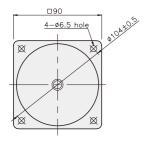


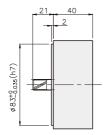
### K9P□BF



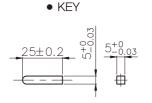
### DECIMAL GEARHEAD

#### K9P10BX





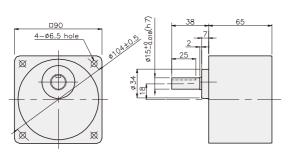
#### **KEY SPEC**



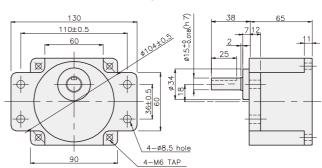


#### GEARHEAD

#### К9Р□В



#### K9P□BF



# **GGM** GGM GEARED MOTOR

## **GEARHEADS**

#### DIMENSIONS

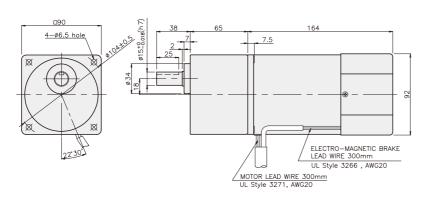
K9□P60F□-B + K9P□B



 $K9 \square P60F \square -B + K9P \square BF$ 



#### K9□P60F□-B + K9P□B



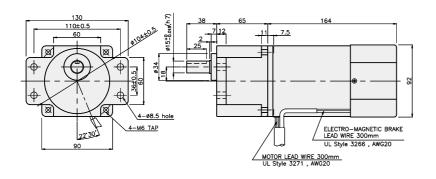
#### DIMENSION TABLE

PART No	L	Application Model	Mounting BOLT
01	65	K9P3~200B	M6 P1.0 X 25
02	40	K9P10BX	M6 P1.0 X 140

#### **WEIGHT**

	PART	WEIGHT(kg)					
	MOTOR	3.08					
DECIMA	AL GEAR HEAD	0,62					
	K9P3∼10B	1,22					
GEAR	K9P12,5~20B	1,32					
HEAD	K9P25~60B	1,42					
	K9P75~200B	1,45					

#### K9□P60F□-B + K9P□BF



## DIMENSION TABLE

PART No	L	Application Model	Mounting BOLT
01	65	K9P3~200BF	M6 P1.0 X 25
02	40	K9P10BX	M6 P1,0 X 65

#### WEIGHT

	PART	WEIGHT(kg)				
	MOTOR	3,08				
DECIMA	L GEAR HEAD	0,62				
	K9P3~10BF	1,22				
GEAR	K9P12,5~20BF	1,30				
HEAD	K9P25~60BF	1,42				
	K9P75~200BF	1,44				