

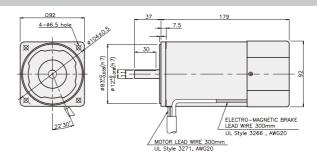
BRAKE MOTOR



□90mm

K9□S90F□-B





90W single-phase: 30 minutes rating, three-phase: continuous rating, four poles

Mode	el	Duty	Voltage (V)	Frequency (Hz)	Current (A)	Start T. (N*m/ Kgf*cm)	Rated T. (N*m/ Kgf*cm)	Speed (rpm)	Condenser (µF)	Friction T. (N*m) (Kgf*cm)
K9R□90FJ-B			100	50	2.52	0,6/6	0.705/7.05	1250	35	1/10
K9K 🗆 90FJ – B			100	60	2,42	0.6/6	0.57/5.7	1550	33	1/10
K9R□90FU-B			110	60	1,88	0.55/5.5	0.57/5.7	1550	25	1/10
RSRESOLO B			115		2,12	0.55/5.5			20	1/10
K9R□90FL-B			200	50	0.9	0.55/5.5	0.705/7.05	1250	8	1/10
TOTAL DOTAL D	single-phase	30 minutes	200	60	1,1	0.00, 0.0	0.57/5.7	1550		1,710
			220	50	1	0.5/5	0.705/7.05	1250		
K9R□90FC-B			220	60	1,1	0.53/5.3	0.57/5.7	1550	7	1/10
Kak Laure-B			230	50	1,3	0,6/6	0.705/7.05	1250	,	1/10
			230	60	1,1	0.0/0	0.57/5.7	1550		
K9R□90FD-B			240	50	0.94	0.55/5.5	0.705/7.05	1250	6	1/10
K9I□90FT-B			200	50	0.79	2.25/22.5	0.65/6.5	1350	_	1/10
K9ILI90FI-B			200	60	0.72	1.75/17.5	0.55/5.5	1600		1/10
			220	50	0.72	2,35/23,5	0.65/6.5	1350		
K9I□90FH-B			220	60	0.63	1.8/18	0.55/5.5	1600	1 _	1/10
Kaimantu-p			230	50	0.86	2,45/24,5	0.65/6.5	1350]	1/10
			230	60	0.66	1,95/19,5	0.55/5.5	1600	1	
K9I□90FM-B	three-phase	a a matimus as sa	380	50	0.43	2,35/23,5	0.65/6.5	1350	_	1/10
K9ILI90FM-B	i iiee-piiase	continuous	380	60	0.37	1,7/17	0.55/5.5	1600	1	1/10
K9I□90FV-B]		400	50	0.52	2,65/26,5	0.65/6.5	1350	_	1/10
KAITAOLA-R			400	60	0.45	2,1/21	0.55/5.5	1600	1 -	1/10
K9I□90FQ-B]		415	50	0.39	2/20	0.68/6.8	1300	_	1/10
NSILISUFQ-B			415	60	0,31	1.5/15	0.55/5.5	1600]	1/10
K9I□90FZ-B			440	50	0.45	2,1/21	0.68/6.8	1300	_	1/10
VAITI AOLY-R			440	60	0.39	1,7/17	0.55/5.5	1600	1	1/10

- * 🗆 : SHAFT SHAPE (S : STRAIGHT, P : PINION) * FH-B which are in end of the model name is UL certified ones.UL FILE NO. E204632
- * 3 phase motor for over 380 voltage can't be used with inverter. Motor winding insulation can be damaged.

50Hz

unit = above : $N \cdot m$ / below : $Kgf \cdot cm$

Model	Speed(rpm)	500	416	300	250	200	166	150	120	100	83	75	60	50	41	37	30	25	20	16	15	12,5	10	8,3	7.5
Motor/ Gearhead	Ratio	3	3,6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
K9□P9	0F□-B	1,58	1,90	2,63	3,16	3,95	4.74	5,27	5,92	7,11	8,53	9.48	10,66	12,79	15,35	17.06	20	20	20	20	20	20	20	20	20
K9P□	B, BF	15.8	19.0	26.3	31.6	39.5	47.4	52.7	59.2	71.1	85,3	94.8	106.6	127.9	153.5	170 <u>.</u> 6	200	200	200	200	200	200	200	200	200

60Hz

unit = above : $N \cdot m$ / below : $Kgf \cdot cm$

Model	Speed(rpm)	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
Motor/ Gearhead	Ratio	3	3.6	5	6	7.5	9	10	12,5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
K9□P9	0F□-B	1,34	1,60	2,23	2.67	3.34	4.01	4.46	5.01	6.01	7.22	8.02	9.02	10,83	12,99	14.43	18.0	20	20	20	20	20	20	20	20
К9Р□	B, BF	13.4	16,0	22,3	26,7	33,4	40.1	44.6	50,1	60,1	72,2	80,2	90,2	108,3	129,9	144,3	180	200	200	200	200	200	200	200	200

- Gearhead and decimal gearhead are sold separately. ★ The code in □ of gearhead model is for gear ratio.
- * color indicates that the output shaft of the geared motor rotates in the same direction as the output shaft of the motor. Others indicate rotation in the opposite direction,
- * If you are to have less ratio than the ratio in the table, you can install the decimal gearhead, which has one tenth of the ratio, between the gearhead and the motor. In this case, the permissible torque is 20N·m/200kgf·cm.

 * RPM is based on motor's synchronous rpm (50HZ:1500rpm, 60HZ:1800rpm) and calculated by dividing gear ratio. Actual rpm is 2~20% less than
- indicating rpm according to load size.





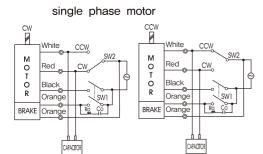
• 50Hz unit = above : N · m / below : kgfcm

Model	Speed(rpm)	500	416	300	250	200	166	150	120	100	82	75	60	50	41	37	30	25	20	16	15	13	10	8.3	7.5
Motor/ Gearhead	Ratio	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
K9□P9	0F□−B	1,58	1,90	2,63	3,16	3,95	4.74	5,27	5,92	7,11	8,53	9.48	10,66	12,79	15,35	17,06	21,32	25,59	30	30	30	30	30	30	30
K9P□E	BU, BUF	15.8	19.0	26,3	31.6	39.5	47.4	52.7	59.2	71,1	85.3	94.8	106,6	127.9	153,5	170,6	213,2	255,9	300	300	300	300	300	300	300

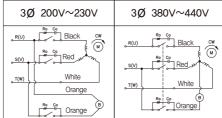
60Hz unit = above : $N \cdot m$ / below : kgfcm

Model	Speed(rpm)	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
Motor/ Gearhead	Ratio	3	3.6	5	6	7.5	9	10	12,5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
K9□P90	0F□-B	1,34	1,60	2,23	2.67	3,34	4.01	4.46	5.01	6.01	7,22	8.02	9.02	10,83	12,99	14.43	18.04	21,65	24,36	30	30	30	30	30	30
K9P□E	BU, BUF	13,4	16,0	22,3	26,7	33.4	40.1	44.6	50,1	60,1	72,2	80,2	90,2	108,3	129,9	144.3	180,4	216,5	243,6	300	300	300	300	300	300

- * Gearhead and decimal gearhead are sold separately, * The code in $\hfill\Box$ of gearhead model is for gear ratio.
- * color indicates that the output shaft of the geared motor rotates in the same direction as the output shaft of the motor. Others indicate rotation in the opposite direction.
- * If you are to have less ratio than the ratio in the table, you can install the decimal gearhead, which has one tenth of the ratio, between the gearhead and the motor. In this case, the permissible torque is 30N·m/300kgfcm.
- * RPM is based on motor's synchronous rpm (50HZ:1500rpm, 60HZ:1800rpm) and calculated by dividing gear ratio. Actual rpm is 2~20% less than indicating rpm according to load size.



three phase motor



connecting two leadwires of U,V,W in turns

*The direction of motor rotation is as viewed from the front shaft end of the motor

Connect Cr circuit for absorbing serge voltage as connection diagram to protect contact point. Ro = $5-200\Omega$ Co = $0.1\sim0.2\mu\text{F}$ 200WV(400WV)



K9P□BF, BUF

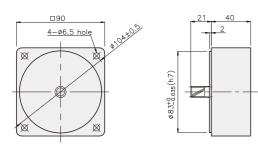


K9P□BU

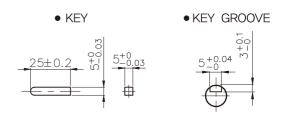


DECIMAL GEARHEAD

K9P10BX

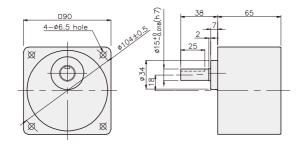


KEY SPEC

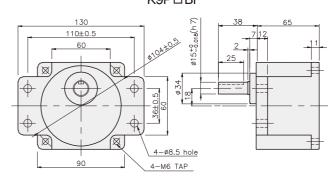


GEARHEAD

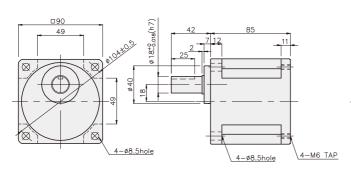
К9Р□В



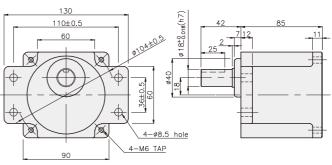
K9P□BF



K9P□BU



K9P□BUF



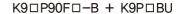
GGM GGM GEARED MOTOR

GEARHEADS

DIMENSIONS

K9□P90F□-B + K9P□B



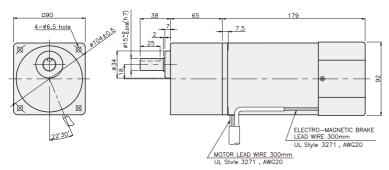




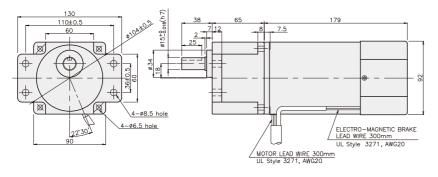




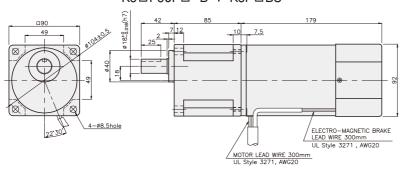
K9□P90F□-B + K9P□B



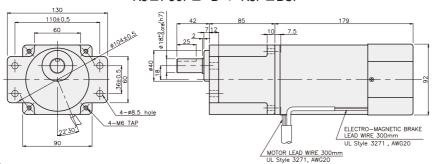
K9□P90F-B + K9P□BF



K9□P90F□-B + K9P□BU



$K9\square P90F\square -B + K9P\square BUF$



WEIGHT

PART	WEIGHT(kg)
MOTOR	3,60
DECIMAL GEAR HEAD	0,62

DIMENSION TABLE

PART No	L	Application Model	Mounting BOLT
01	65	K9P3~200B	M6 P1,0 X 95
02	40	K9P10BX	M6 P1.0 X 140

WEIGHT

PART	WEIGHT(kg)
K9P3~10B	1,22
K9P12,5~20B	1,32
K9P25~60B	1,42
K9P75~200B	1,45

DIMENSION TABLE

PART No	L	Application Model	Mounting BOLT
01	65	K9P3∼200BF	M6 P1.0 X 25
02	40	K9P10BX	M6 P1,0 X 65

WEIGHT

PART	WEIGHT(kg)
K9P3~10BF	1,22
K9P12,5~20BF	1,30
K9P25~60BF	1,42
K9P75~200BF	1,44

DIMENSION TABLE

PART No	L	Application Model	Mounting BOLT
01	85	K9P3~200BU	M6 P1.0 X 20
02	40	K9P10BX	M6 P1,0 X 60

WEIGHT

PART	WEIGHT(kg)
K9P3~10BU	1,44
K9P12,5~20BU	1,55
K9P25~60BU	1,69
K9P75~200BU	1,74

DIMENSION TABLE

PART No	L	Application Model	Mounting BOLT
01	85	K9P3~200BUF	M6 P1.0 X 20
02	40	K9P10BX	M6 P1.0 X 65

WEIGHT

WEIGHT			
PART	WEIGHT(kg)		
K9P3~10BUF	1,50		
K9P12,5~20BUF	1,62		
K9P25~60BUF	1,76		
K9P75~200BUF	1,82		